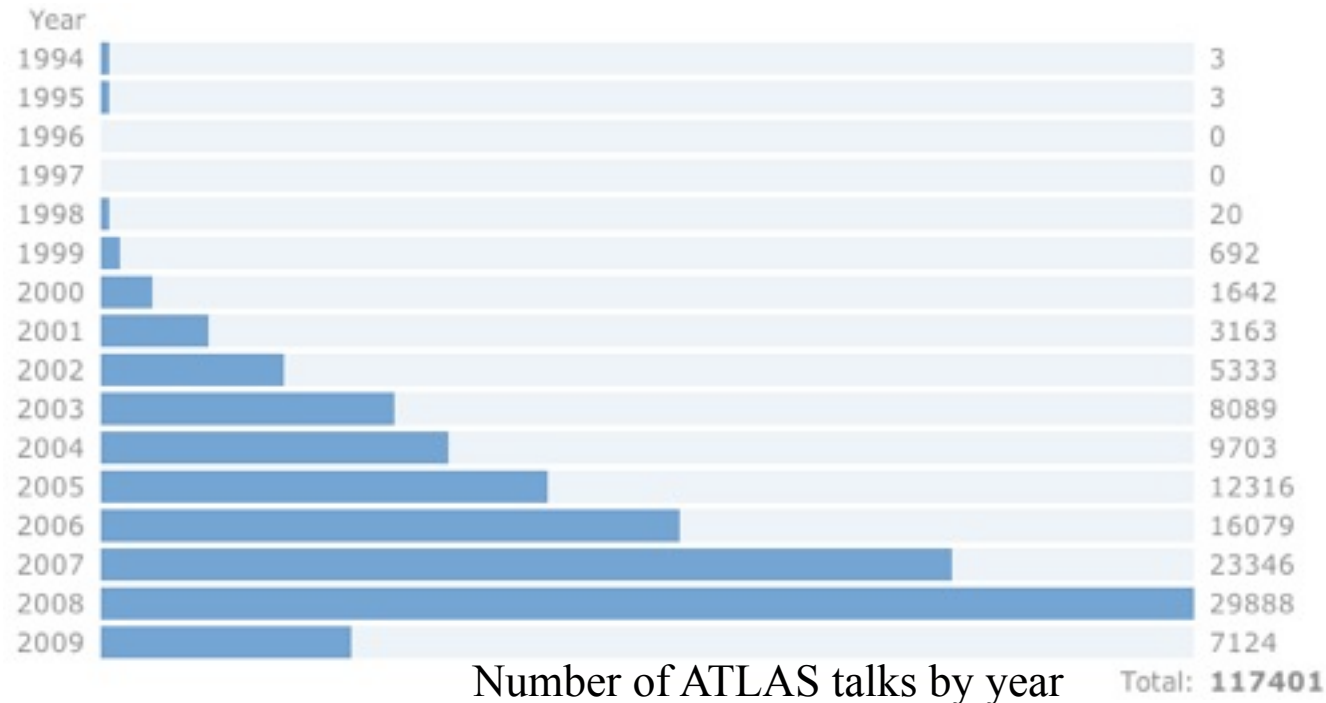




~~Modern statistics -- how can we gain some intuition?~~

# ***Including Systematics and New ways to Publishing - are they useful?***

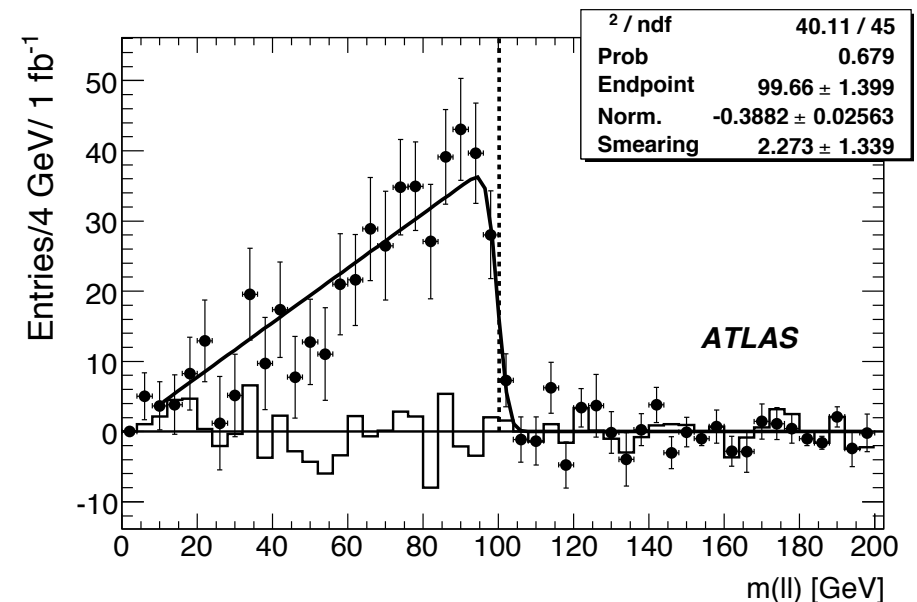
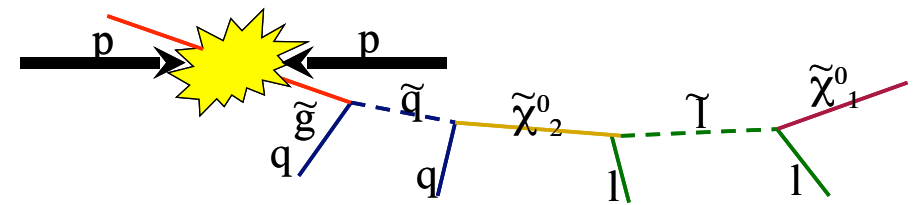
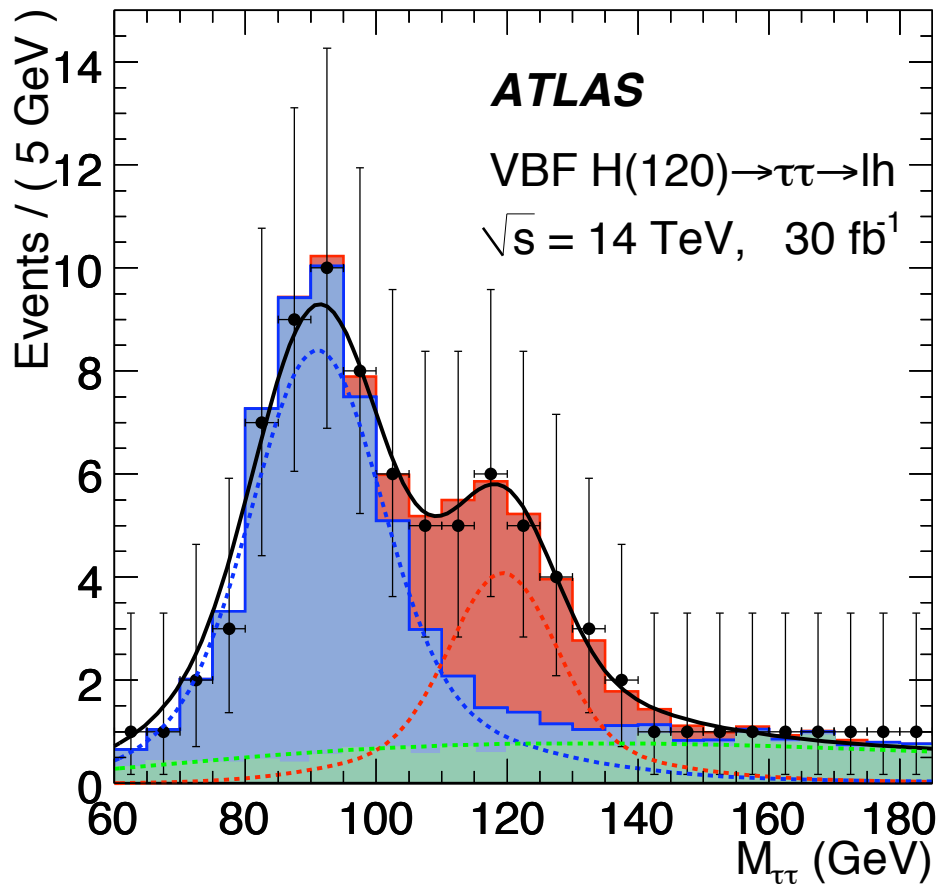


# What's the Model



Beyond just providing histograms, any inference that we do will bring in some type of model for the data.

- What are the models in these two specific examples?

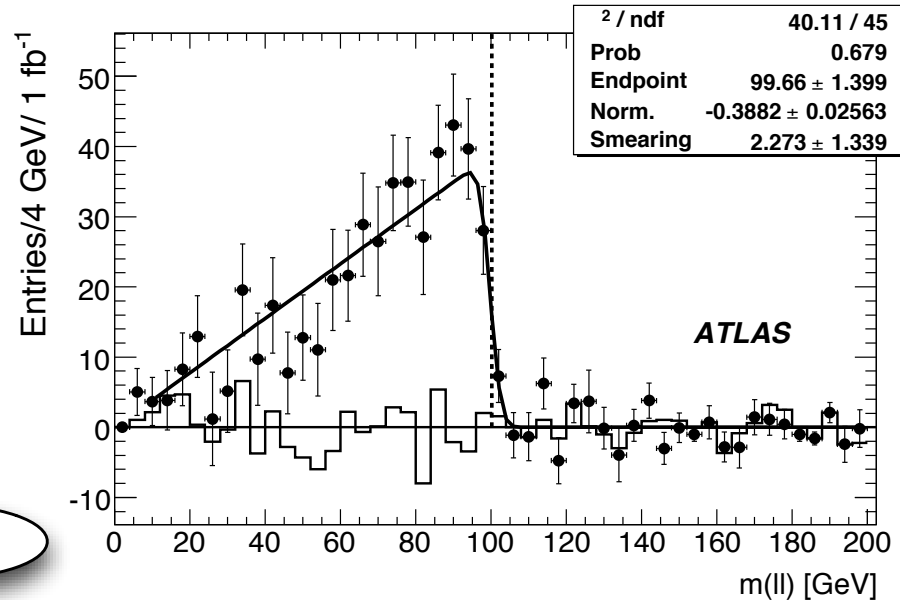


# A graphical representation

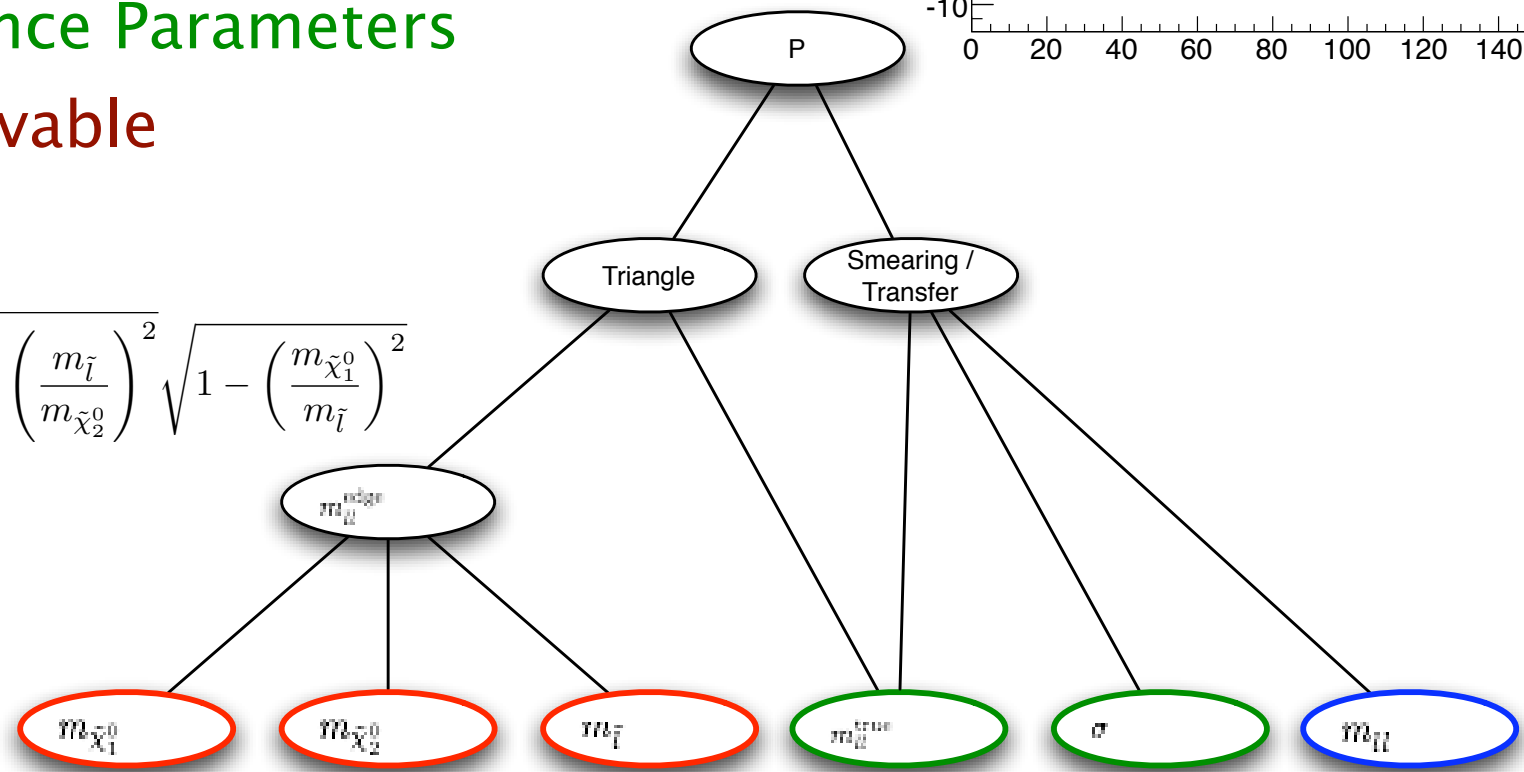


Here is a graphical representation of this model that outlines its structural relationships

- Functions
- Parameters of Interest
- Nuisance Parameters
- Observable



$$m_{ll}^{\text{edge}} = m_{\tilde{\chi}_2^0} \sqrt{1 - \left(\frac{m_{\tilde{l}}}{m_{\tilde{\chi}_2^0}}\right)^2} \sqrt{1 - \left(\frac{m_{\tilde{\chi}_1^0}}{m_{\tilde{l}}}\right)^2}$$



$$P(m_{ll} | m_{\tilde{\chi}_1^0}, m_{\tilde{\chi}_2^0}, m_{\tilde{l}}, \sigma) = \text{Triangle}(m_{ll}^{\text{true}}, m_{ll}^{\text{edge}}(m_{\tilde{\chi}_1^0}, m_{\tilde{\chi}_2^0}, m)) \oplus \text{Smearing}(m_{ll}^{\text{true}}, m_{ll})$$

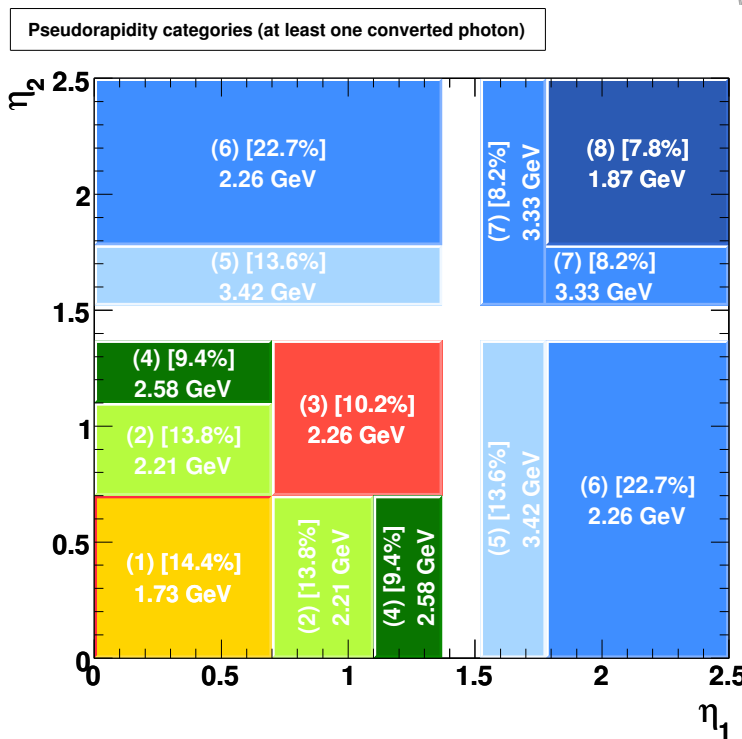
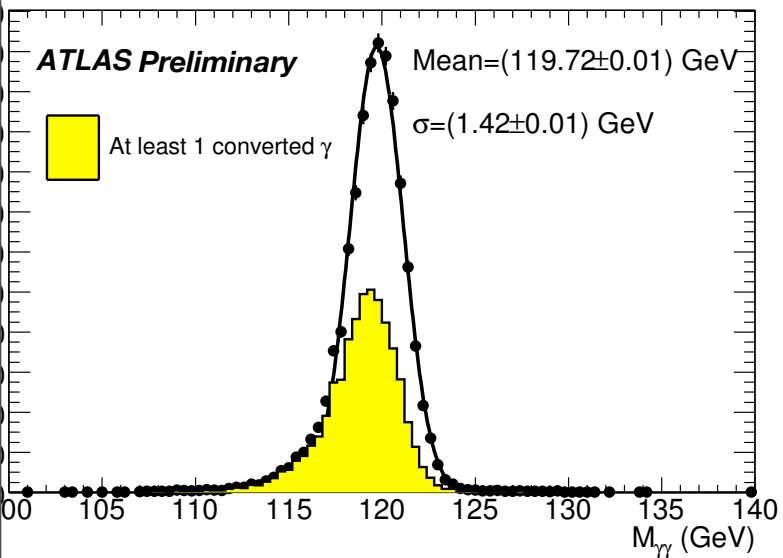
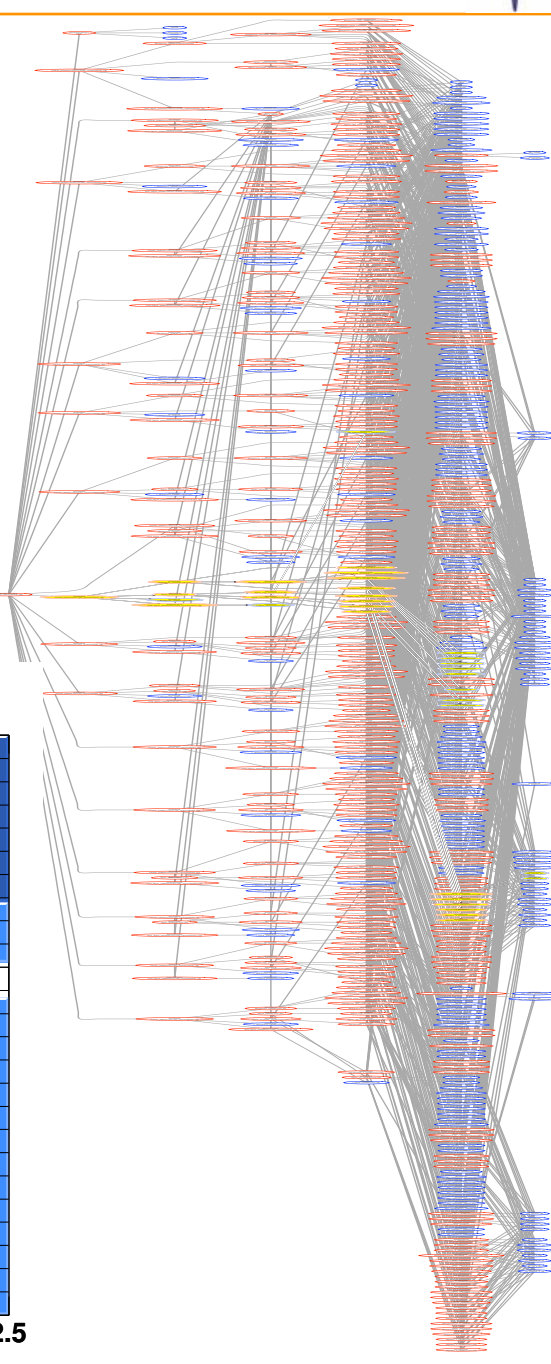


# What's the Model

ATLAS fits to the  $M_{\gamma\gamma}$  spectrum are categorized by the number of jets x conversion status x rapidity region

Similar sensitivity as CMS result

Complex model represented by this graph (automatically generated by RooFit/RooStats)



# Matrix Element Method as a Parametrization



With the same di-lepton mass distribution, we can either:

- ▶ relate edge according to:

$$m_{ll}^{\text{edge}} = m_{\tilde{\chi}_2^0} \sqrt{1 - \left(\frac{m_{\tilde{l}}}{m_{\tilde{\chi}_2^0}}\right)^2} \sqrt{1 - \left(\frac{m_{\tilde{\chi}_1^0}}{m_{\tilde{l}}}\right)^2}$$

- ▶ incorporate matrix element techniques

Matrix-element likelihood:

Calculate probability directly

$$P(\text{event } z \mid \text{SM}) = P(z \mid \text{process A}) + P(z \mid \text{process B}) + \dots$$

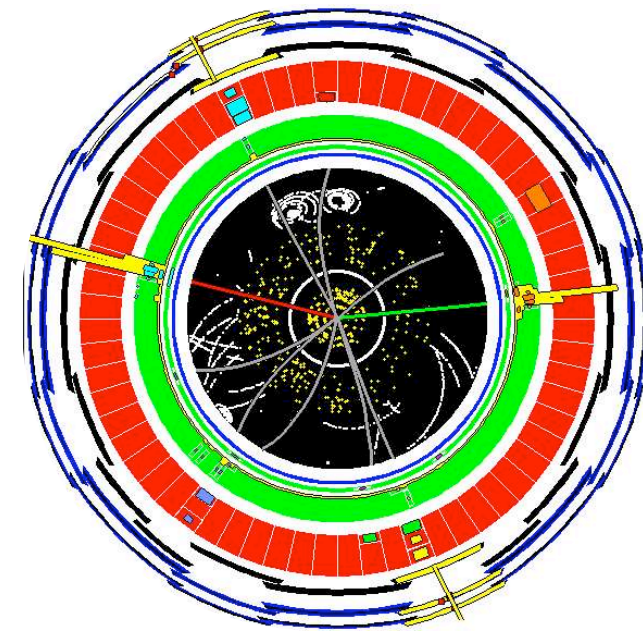
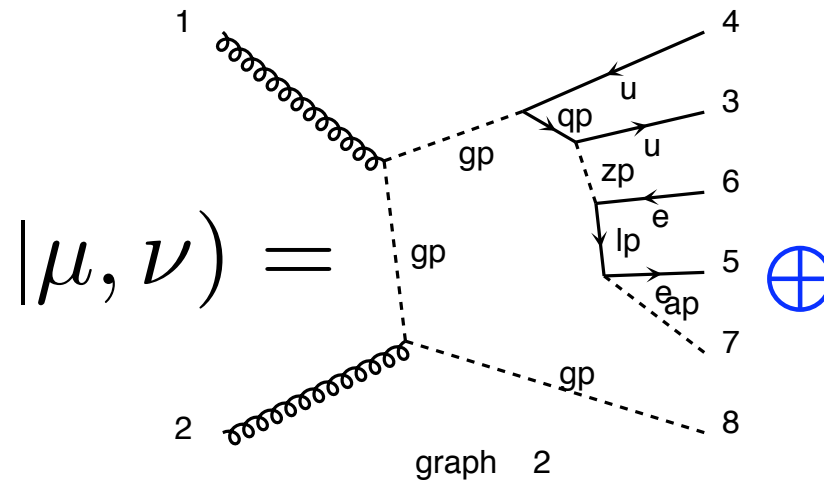
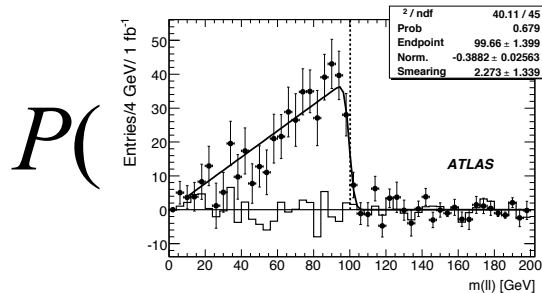
where

$$P(z \mid A) = \int dy |\mathcal{M}_A|^2 f_p f_p f_{\text{TF}}(y,z) = d\sigma_A/dz$$

Parton(y) to detector(z) transfer function (TF) describes parton-shower and detector response in parametrized form (*Issue 2*)

Matrix-element\*PDFs for process A (*Issue 2*)

Integration over parton-level quantities



# Matrix Element Method as a Parametrization



With the same di-lepton mass distribution, we can either:

- ▶ relate edge according to:

$$m_{ll}^{\text{edge}} = m_{\tilde{\chi}_2^0} \sqrt{1 - \left(\frac{m_{\tilde{l}}}{m_{\tilde{\chi}_2^0}}\right)^2} \sqrt{1 - \left(\frac{m_{\tilde{\chi}_1^0}}{m_{\tilde{l}}}\right)^2}$$

- ▶ incorporate matrix element techniques
  - naturally, could include more kinematic info → more power.

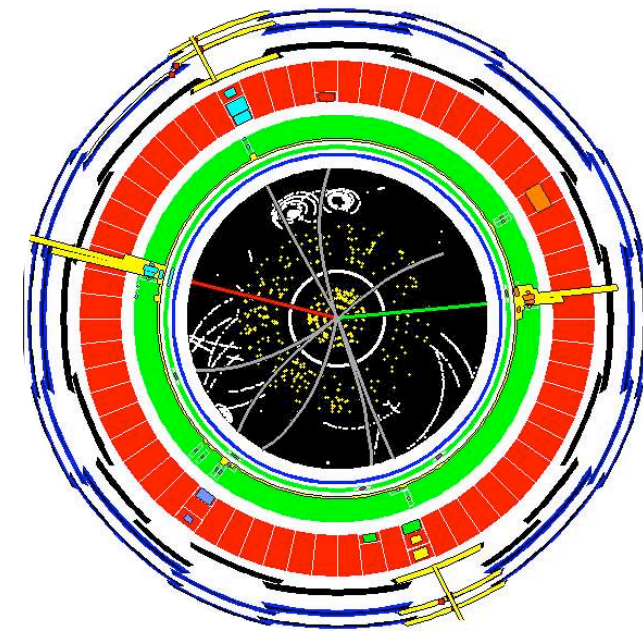
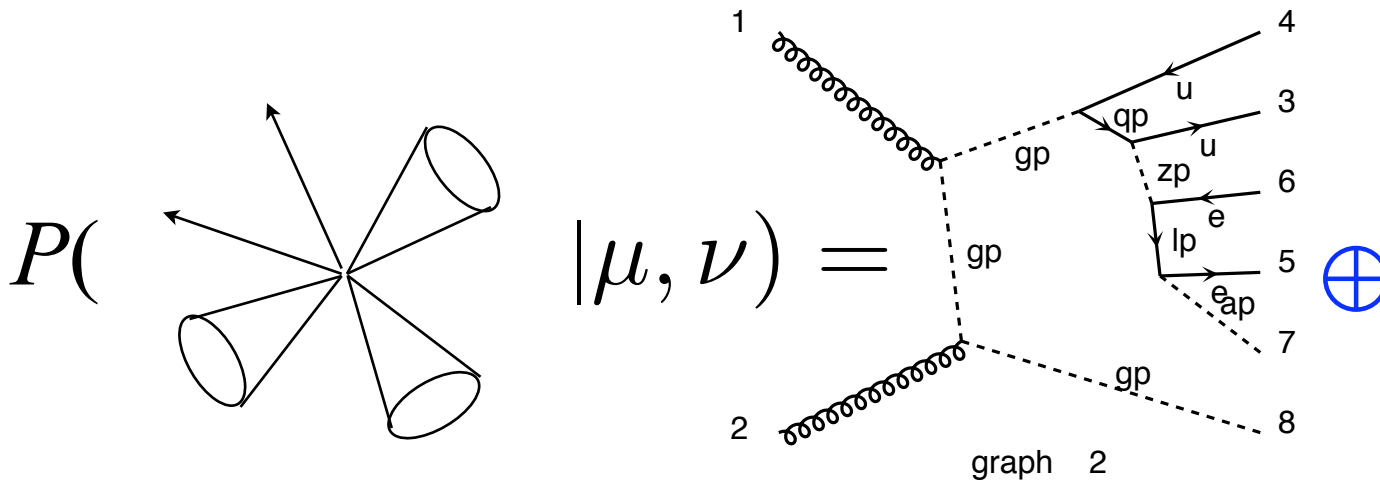
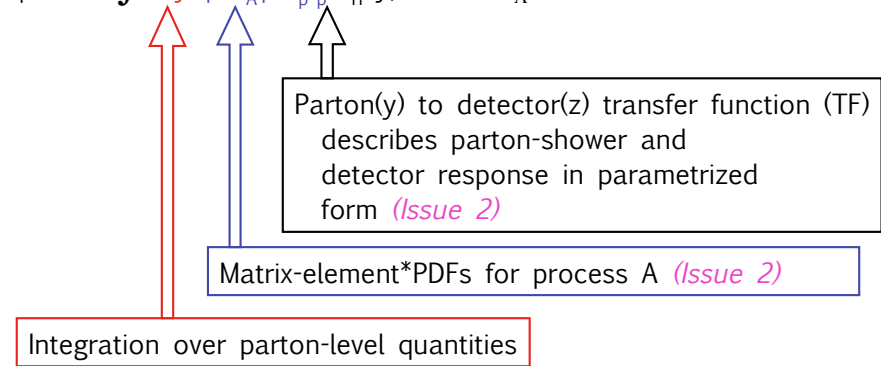
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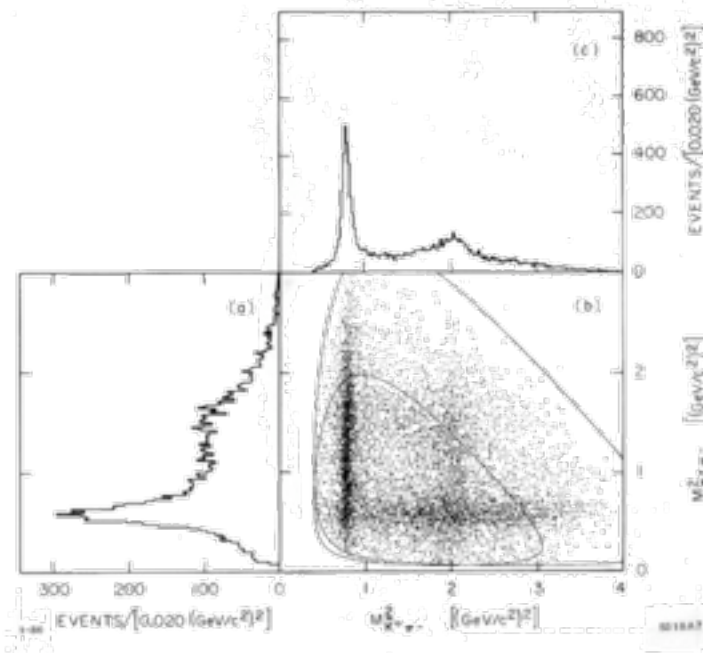


# Matrix Element vs. Purely Kinematic Features

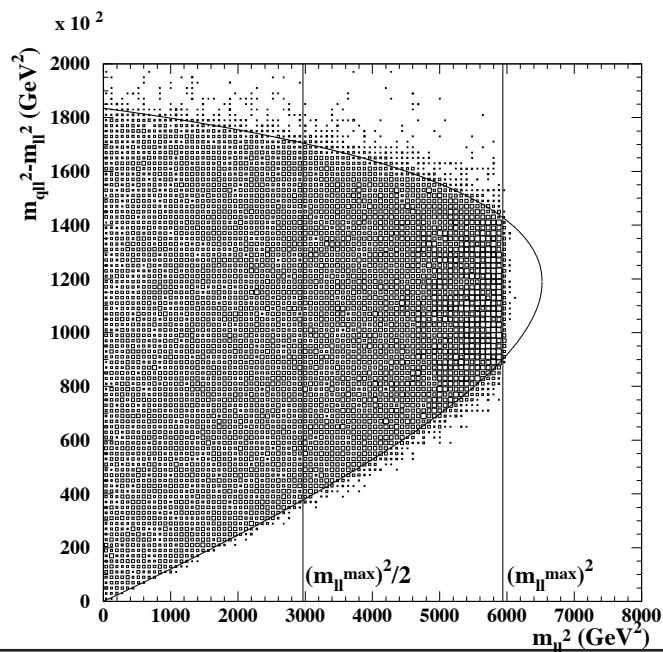


Tuesday, we had a nice discussion about unifying kinematic features (eg. edges, MT2, hybrid method, etc.) in terms of likelihood-ratio inspired observables restricted to boundaries in phase space (or other well-defined features)

- less dependence on  $|\mathcal{M}|^2$  across phase space
- basically generalizations of Dalitz plots



Tovey, Costanzo [arXiv:0902.2331]

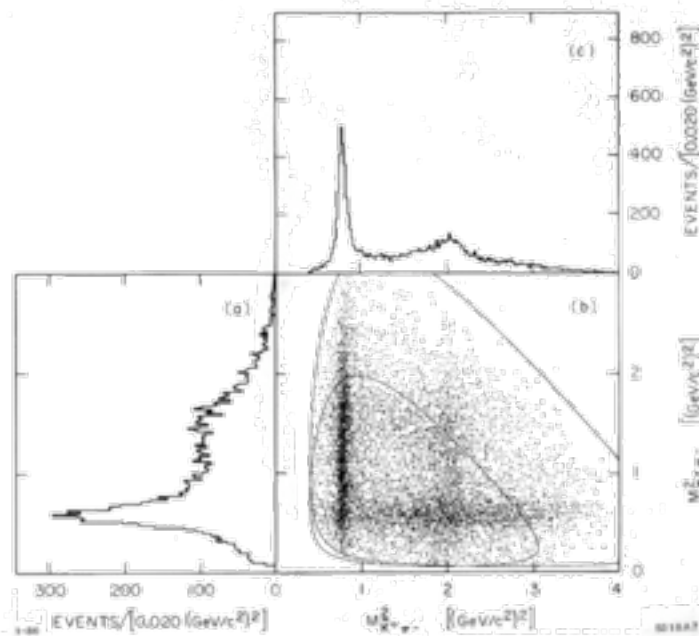


# Matrix Element vs. Purely Kinematic Features

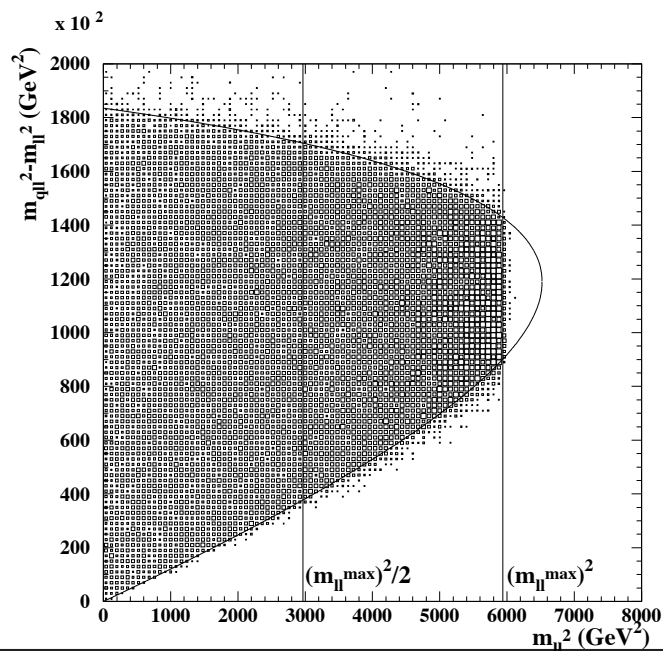


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- less dependence on  $|\mathcal{M}|^2$  across phase space
- basically generalizations of Dalitz plots
- ... I remembered that  $J^P$  of parent can lead to vanishing densities near kinematic endpoints.



Tovey, Costanzo [arXiv:0902.2331]



| Spin           | I = 0 | I = 1<br>(except 3=0) | I = 2<br>=+ =- =0 | other modes | I = 1<br>(3=0 only)<br>and I = 3 |
|----------------|-------|-----------------------|-------------------|-------------|----------------------------------|
| 0 <sup>-</sup> |       |                       |                   |             |                                  |
| 1 <sup>+</sup> |       |                       |                   |             |                                  |
| 2 <sup>-</sup> |       |                       |                   |             |                                  |
| 3 <sup>+</sup> |       |                       |                   |             |                                  |
| 1 <sup>-</sup> |       |                       |                   |             |                                  |
| 2 <sup>+</sup> |       |                       |                   |             |                                  |
| 3 <sup>-</sup> |       |                       |                   |             |                                  |

FIG. 2. Regions of the  $3\pi$  Dalitz plot where the density must vanish because of symmetry requirements are shown in black. The vanishing is of higher order (stronger) where black lines and dots overlap. In each isospin and parity state, the pattern for a spin of  $J+$  even integer is identical to the pattern for spin  $J$ , provided  $J \geq 2$ . (Exception: vanishing at the center is not required for  $J \geq 4$ .)



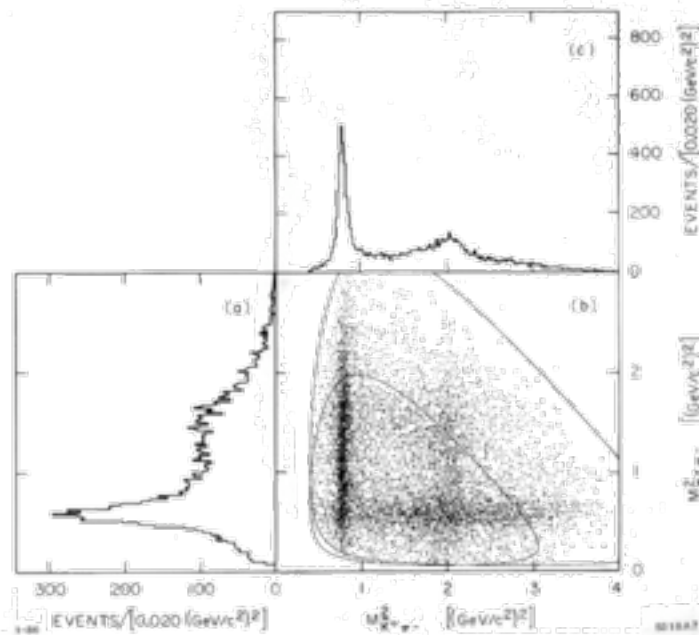
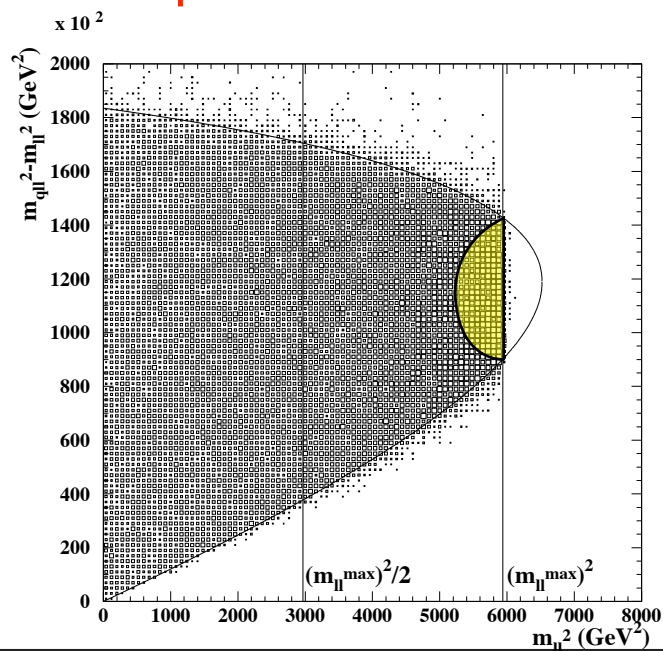
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Tuesday, we had a nice discussion about unifying kinematic features (eg. edges, MT2, hybrid method, etc.) in terms of likelihood-ratio inspired observables restricted to boundaries in phase space (or other well-defined features)

- less dependence on  $|\mathcal{M}|^2$  across phase space
- basically generalizations of Dalitz plots
- ... I remembered that  $J^P$  of parent can lead to vanishing densities near kinematic endpoints.
- Don't see holes without spin. Could this lead to "false endpoints" due to M.E. suppression?

Tovey, Costanzo [arXiv:0902.2331]



| Spin           | I = 0 | I = 1<br>(except 3=0) | I = 2<br>+ + - - = 0<br>other modes | I = 1<br>(3=0 only)<br>and I = 3 |
|----------------|-------|-----------------------|-------------------------------------|----------------------------------|
| 0 <sup>-</sup> |       |                       |                                     |                                  |
| 1 <sup>+</sup> |       |                       |                                     |                                  |
| 2 <sup>-</sup> |       |                       |                                     |                                  |
| 3 <sup>+</sup> |       |                       |                                     |                                  |
| 1 <sup>-</sup> |       |                       |                                     |                                  |
| 2 <sup>+</sup> |       |                       |                                     |                                  |
| 3 <sup>-</sup> |       |                       |                                     |                                  |

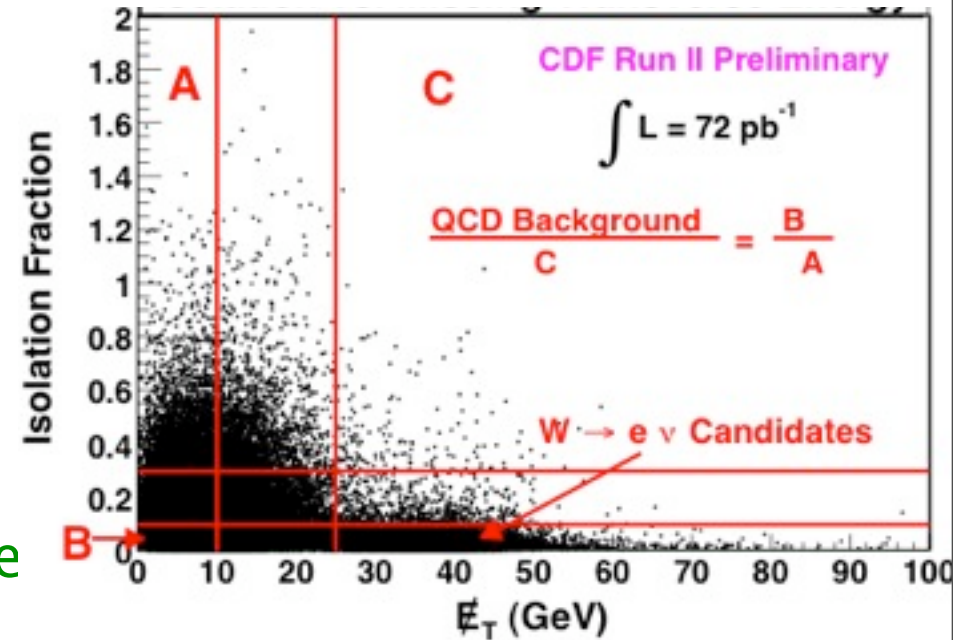
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# Data Driven SUSY Background Estimation

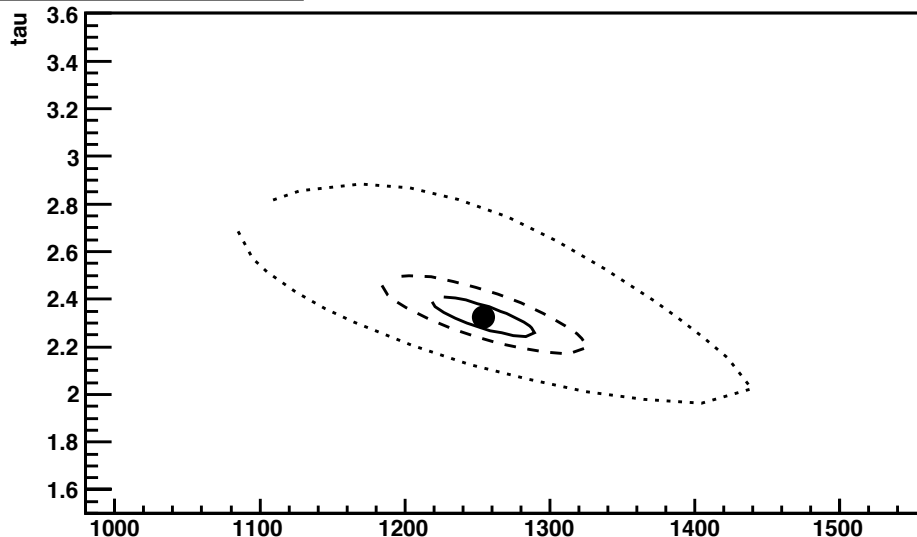


Even simple number-counting type analyses have a model.

- ▶ Background is estimated as  $B/A * C$ 
  - simple propagation of errors misses across Poisson gives non-Gaussian correlations
  - Given measurements in A,B,C,D we can see contours with clear non-Gaussian correlations



Histogram of contourPlot\_bCont\_tau



```
RootRealVar s("s", "s", _x-_y, 0., 200.);
RootRealVar b("b", "b", _y*_xCont/_yCont, 0., 500.);
RootRealVar tau("tau", "tau", _yCont/_xCont, 0, 5);
RootRealVar bCont("bCont", "b control", _xCont, 0., 2000.);

RootFormulaVar splusb("splusb", "s+b", RooArgSet(s, b));
RootProduct bTau("bTau", "b*tau", RooArgSet(b, tau));
RootProduct bContTau("bContTau", "bCont*tau", RooArgSet(bCont, tau));
RootRealVar x("x", "x", _x, 0., 1000.);
RootRealVar y("y", "y", _y, 0., 1000.);
RootRealVar yCont("yCont", "y Control", _yCont, 0., 3000.);
RootRealVar xCont("xCont", "x Control", _xCont, 0., 3000.);

RootPoisson sigRegion("sigRegion", "sigRegion", x, splusb);
RootPoisson sideband("sideband", "sideband", y, bTau);
RootPoisson xContDist("xContDist", "xCont dist", xCont, bCont);
RootPoisson yContDist("yContDist", "yCont dist", yCont, bContTau);

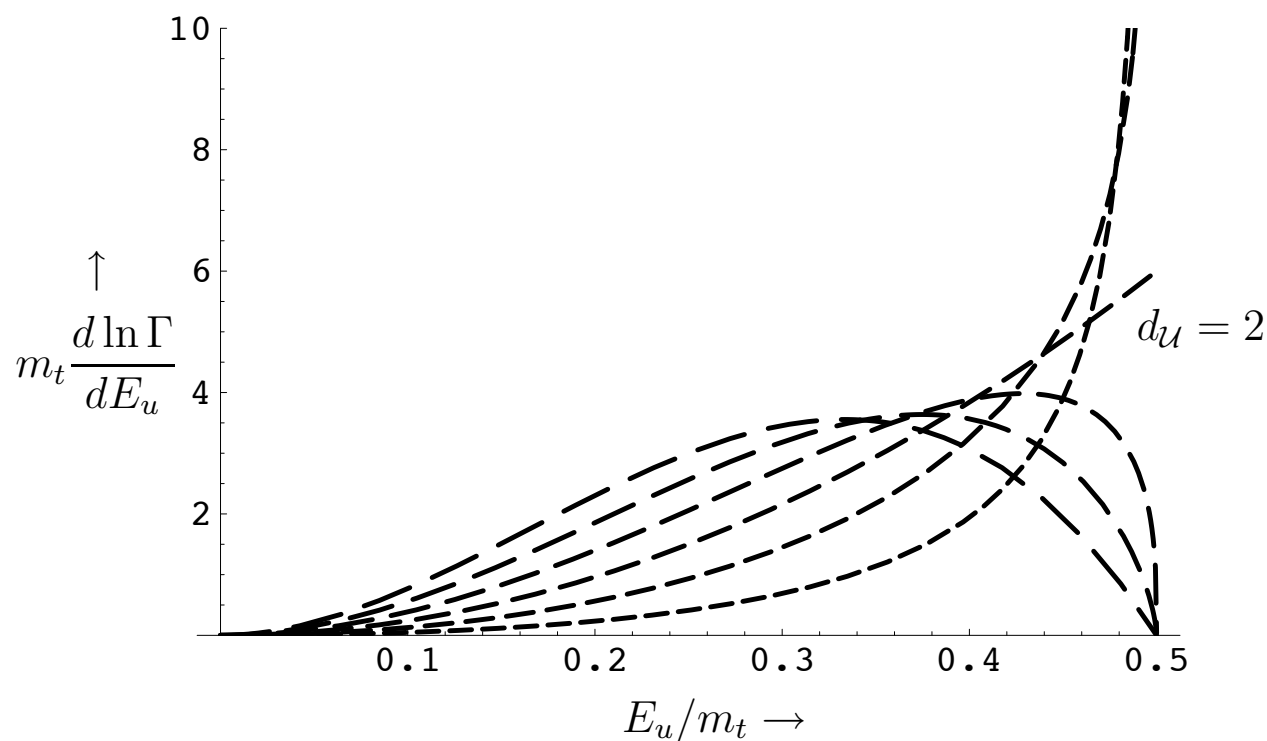
RootProdPdf joint("joint", "joint", RooArgSet(sigRegion, sideband,
xContDist, yContDist) );
```

# Unparticle have models too



While we've been talking about Matrix Element methods and Feynman-diagram like models for new physics...

... unparticles have models too.



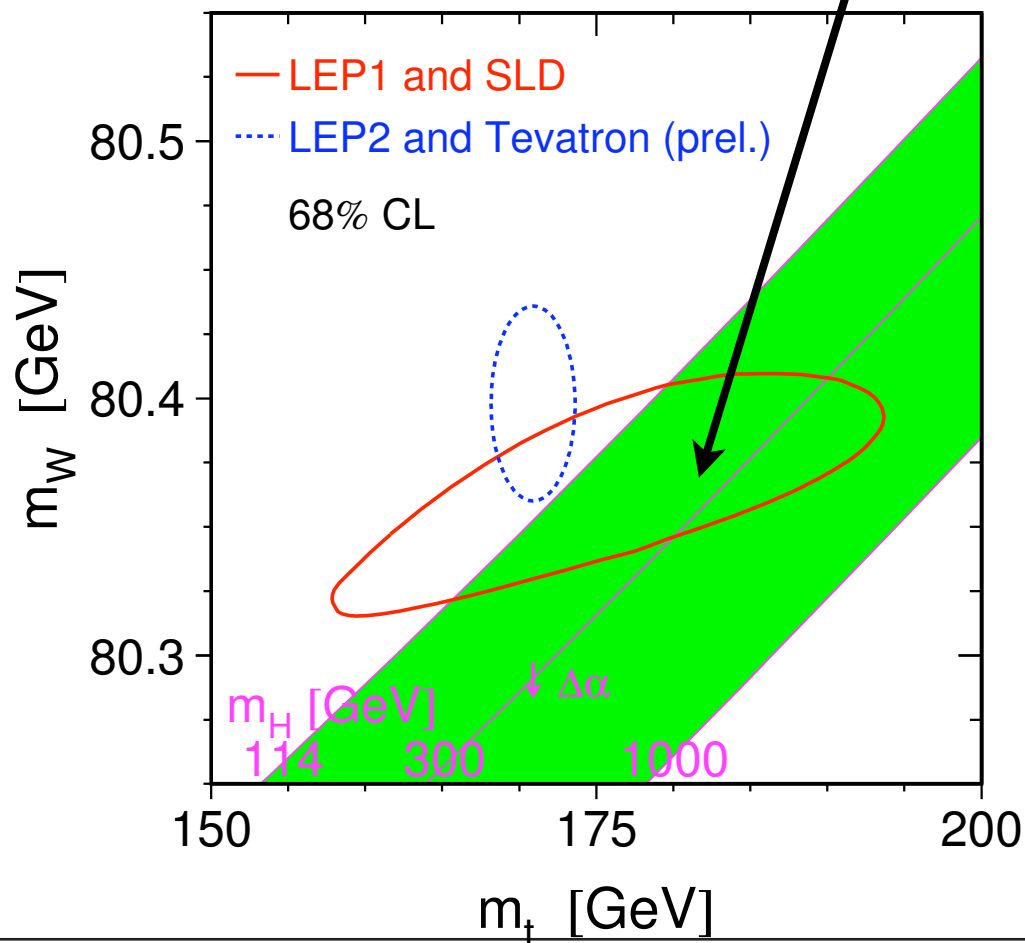
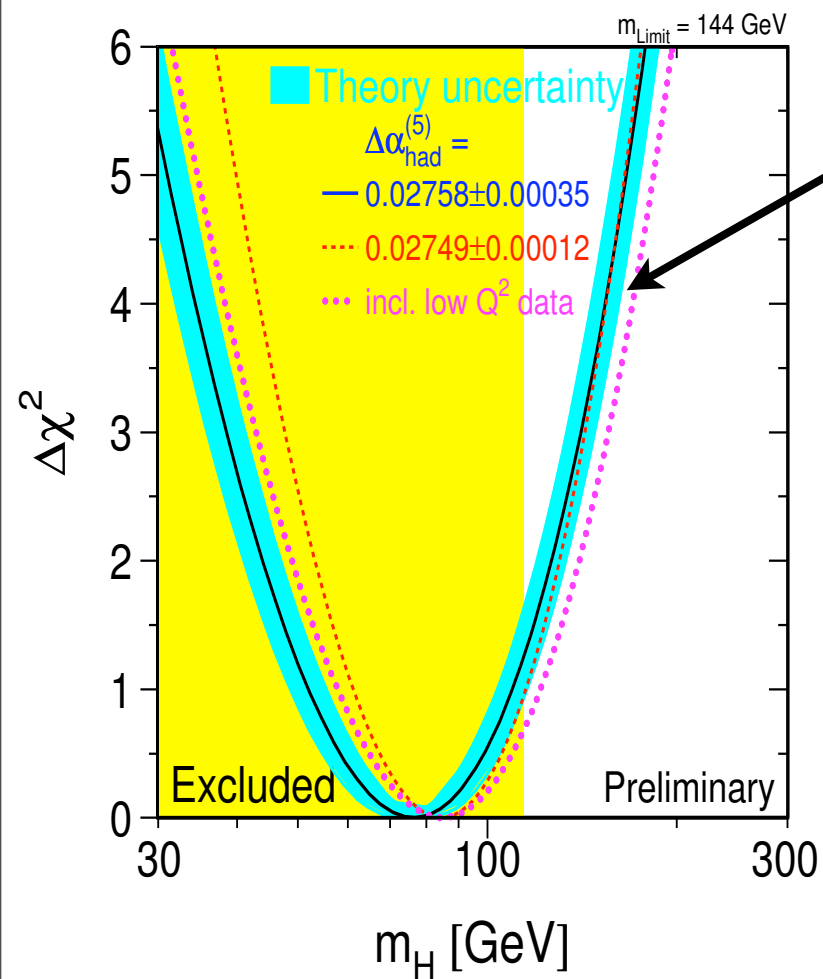
# Examples of Published Likelihoods



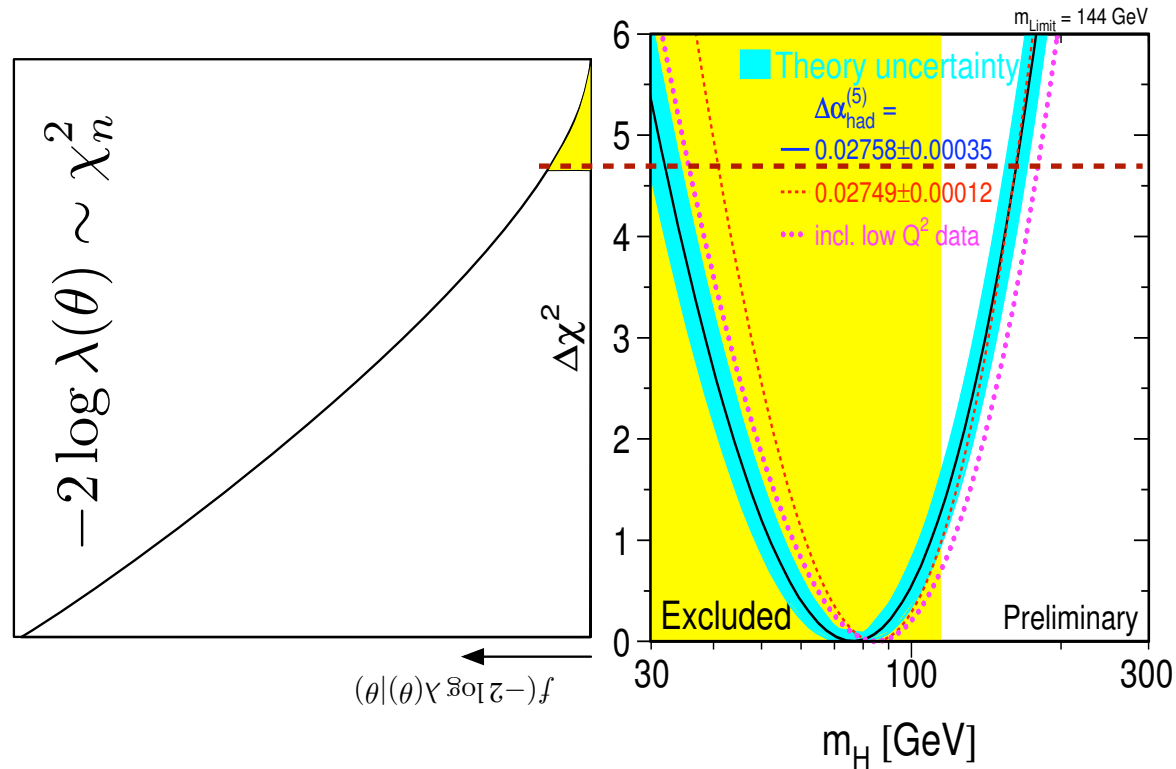
Eventually, we will aim to publish some likelihood functions of measured parameters.

You can find examples of published likelihoods in 1D

In 2-D you just get the contours



# Likelihood-based Intervals



Let's recall quickly the logic of limits derived from these types of likelihood curves.

A certain value of  $-2 \log \lambda(\mu)$  corresponds to a  $\chi^2$

We know the  $\chi^2$  distribution, so we can translate to a 95% limit

# Likelihood-based Intervals

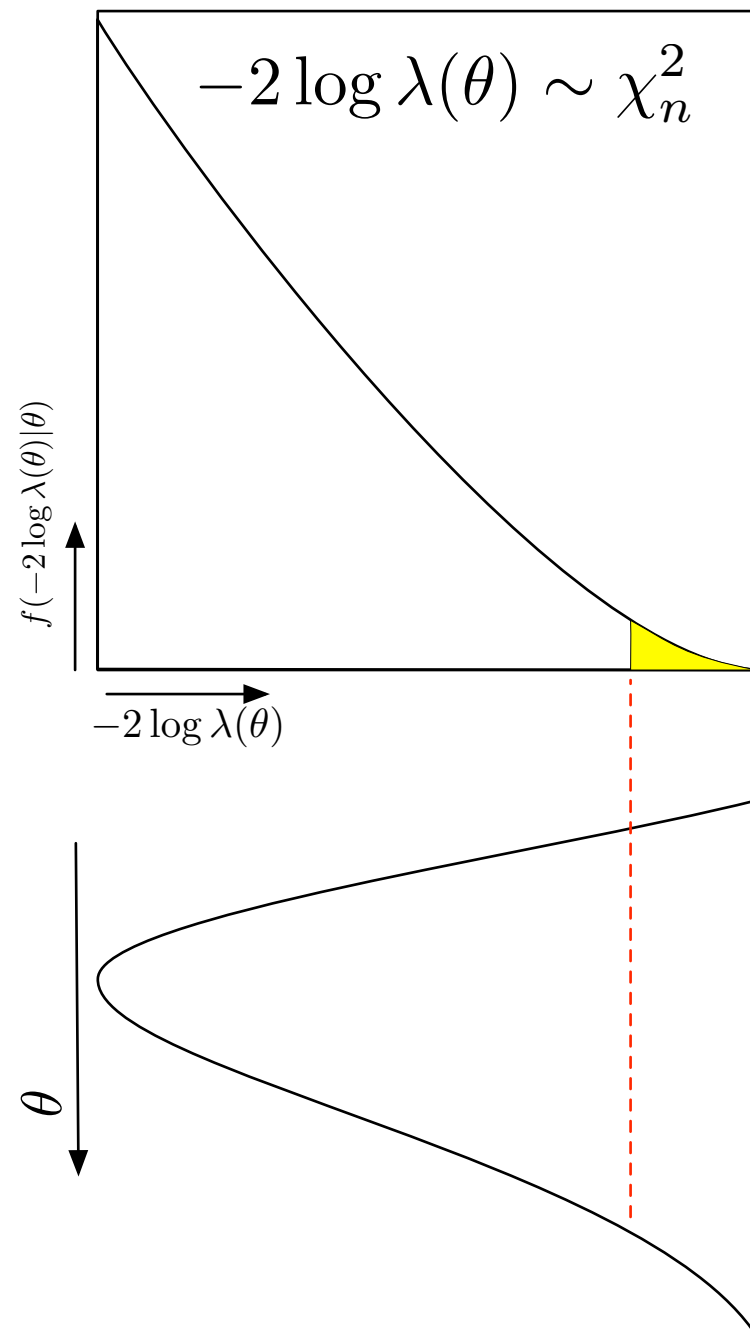


Wilks's theorem tells us how the profile likelihood ratio is distributed

- ▶ asymptotically it is  $\chi^2$
- ▶ there are some restrictions on the parametrized family of models
  - eg. boundaries & look-elsewhere

For these limits to be right, the model needs to include the 'true distribution':

- ▶ eg. what is actually producing the data
- ▶ eg. nature + our real detectors





# Systematics, Systematics, Systematics



# Incorporating Systematics by “Profiling”



Let  $\mu$  be the parameters we are interested in

Let  $\nu$  be the rest of them (nuisance parameters)

Let  $\hat{\nu}$  be the best fit to the data

Let  $\hat{\nu}(\mu)$  be the best fit to the data with  $\mu$  constrained

Consider the profile likelihood ratio

$$\lambda(\mu) = \frac{P(\text{data}|\mu, \hat{b}(\mu), \hat{\nu}(\mu))}{P(\text{data}|\hat{\mu}, \hat{b}, \hat{\nu})}$$

one can see the **function** is independent of true values of

- ▶ **though its distribution** might depend indirectly

Again, if the model includes the true distribution, then we know its distribution:  $-2 \log \lambda(\mu) \sim \chi_N^2$

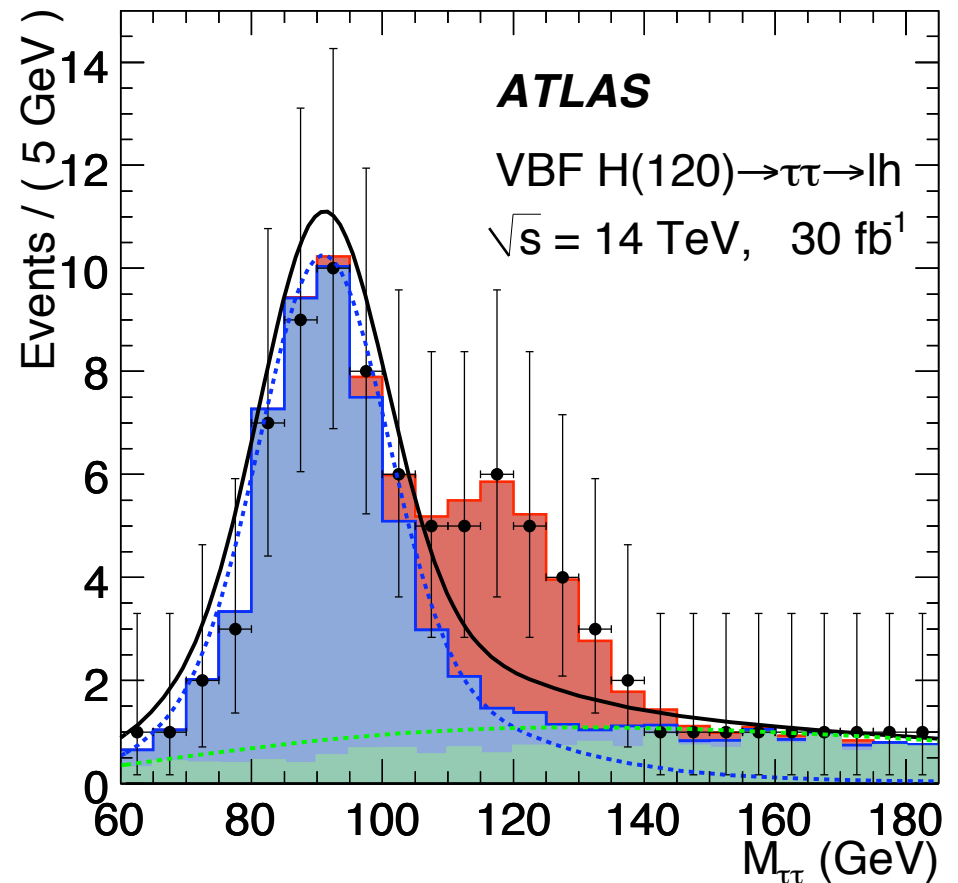
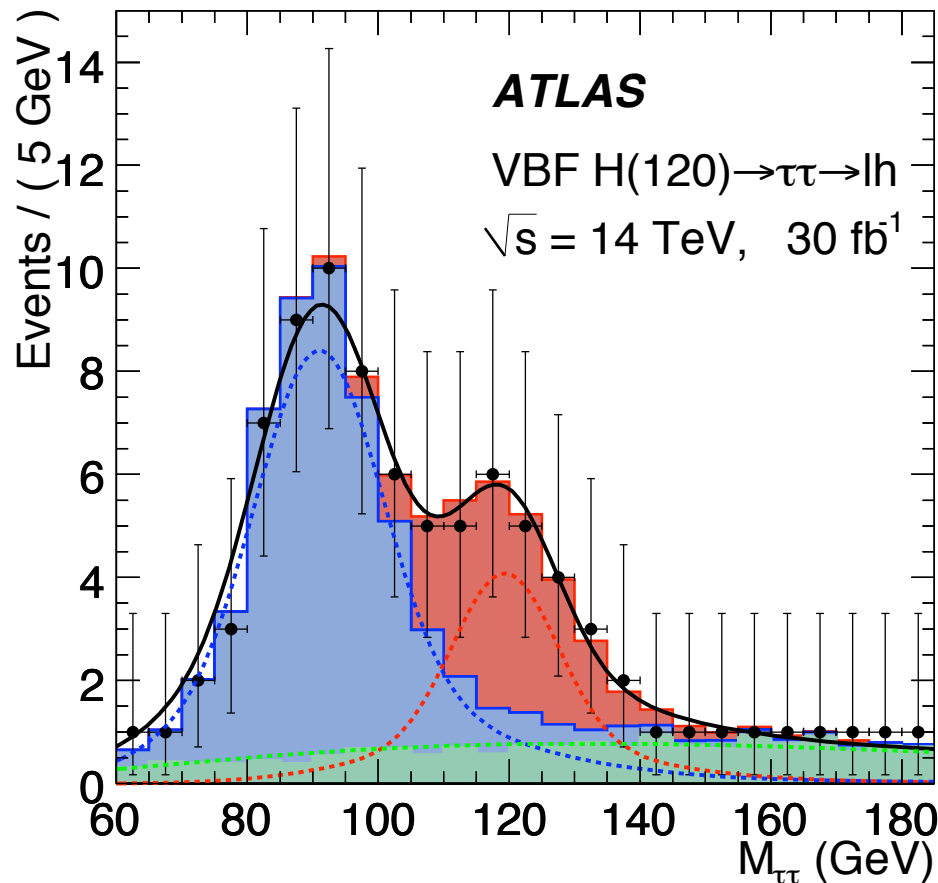


# An example



Essentially, you need to fit your model to the data twice:  
once with everything floating, and once with signal fixed to 0

$$\lambda(\mu = 0) = \frac{L(\text{data} | \mu = 0, \hat{b}(\mu = 0), \hat{v}(\mu = 0))}{L(\text{data} | \hat{\mu}, \hat{b}, \hat{v})} \cdot \frac{L(\text{data} | \mu = 0, \hat{b}, \hat{v})}{L(\text{data} | \hat{\mu}, \hat{b}, \hat{v})}$$



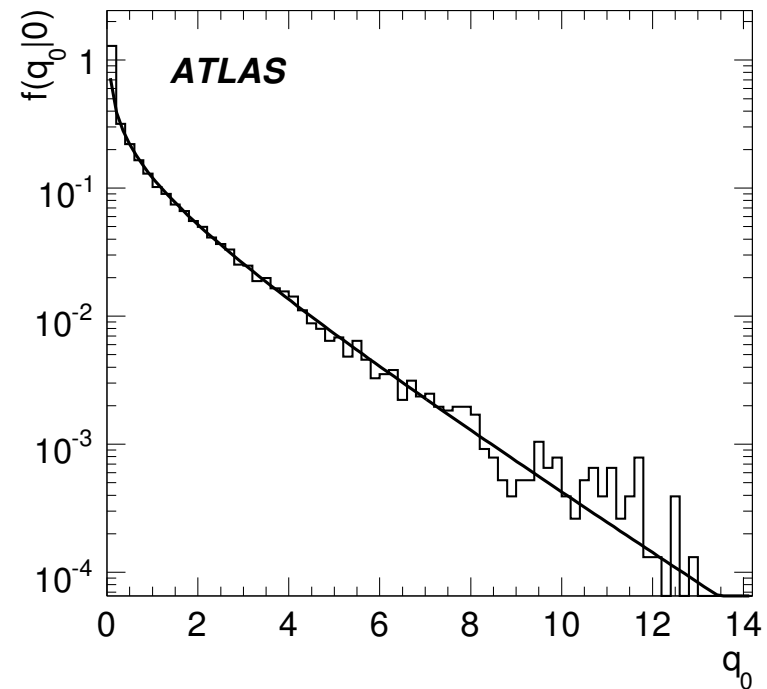
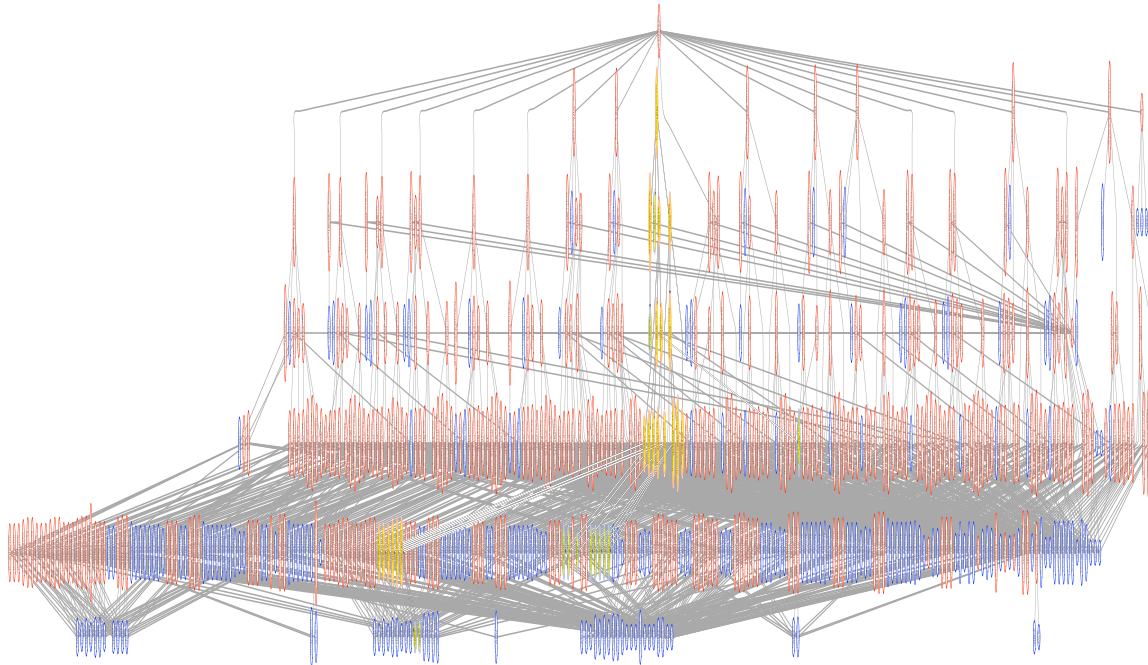


An recent ATLAS Higgs example:

- ▶ even with very complicated pdf, distribution looks  $\chi^2$

$$\lambda(\mu = 0) = \frac{L(\text{data} | \mu = 0, \hat{b}(\mu = 0), \hat{v}(\mu = 0))}{L(\text{data} | \hat{\mu}, \hat{b}, \hat{v})},$$

$$q_0 = -2 \log \lambda(\mu = 0)$$



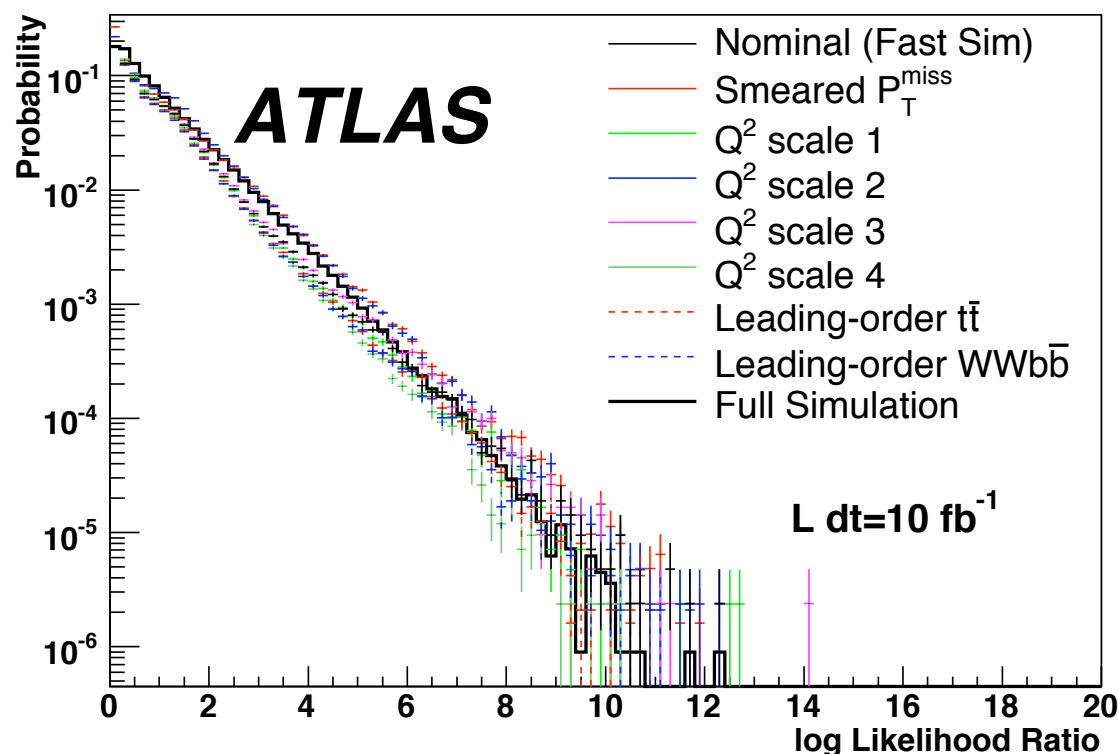
# Experimentalist Justification



So far this looks a bit like magic. How can you claim that you incorporated your systematic just by fitting the best value of your uncertain parameters and making a ratio?

It won't unless the parametrization is sufficiently flexible.

So check by varying the settings of your simulation, and see if the profile likelihood ratio is still distributed as a chi-square



Here it is pretty stable, but it's not perfect (and this is a log plot, so it hides some pretty big discrepancies)

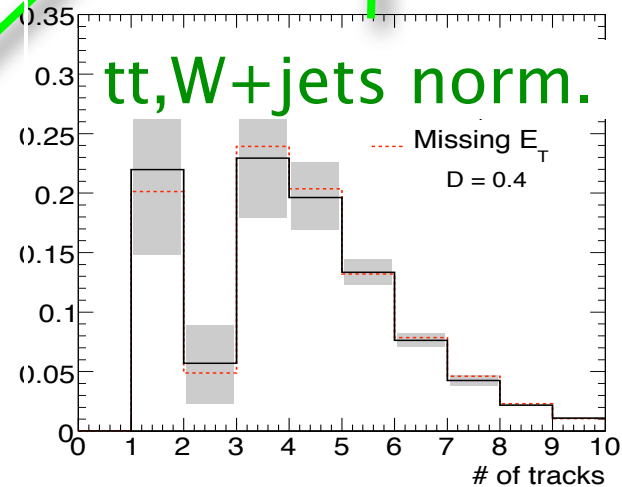
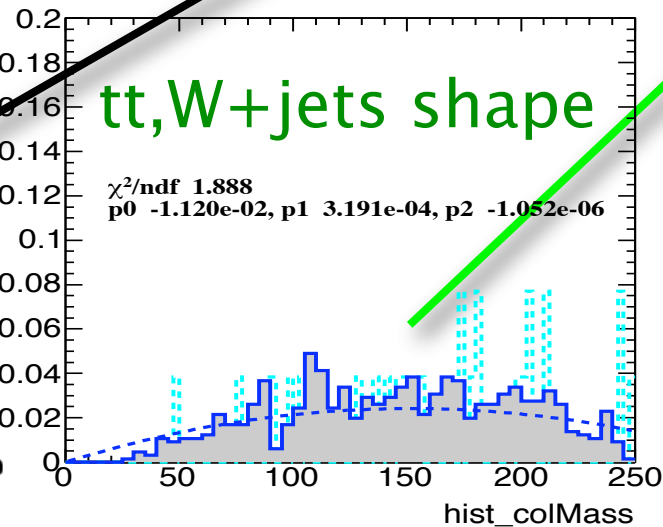
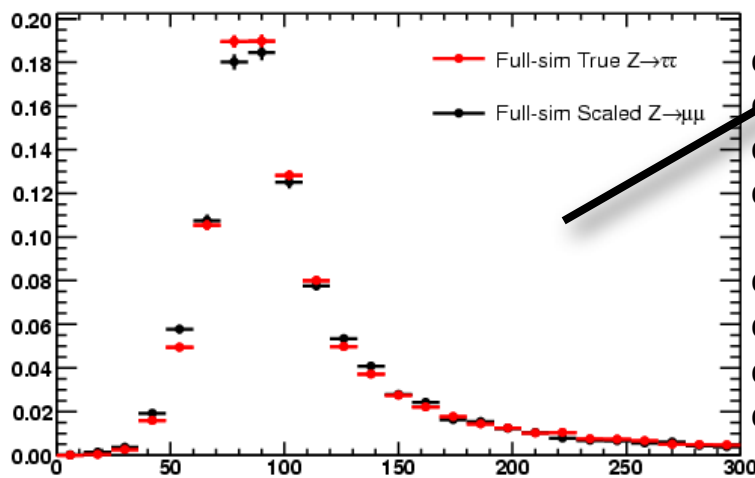
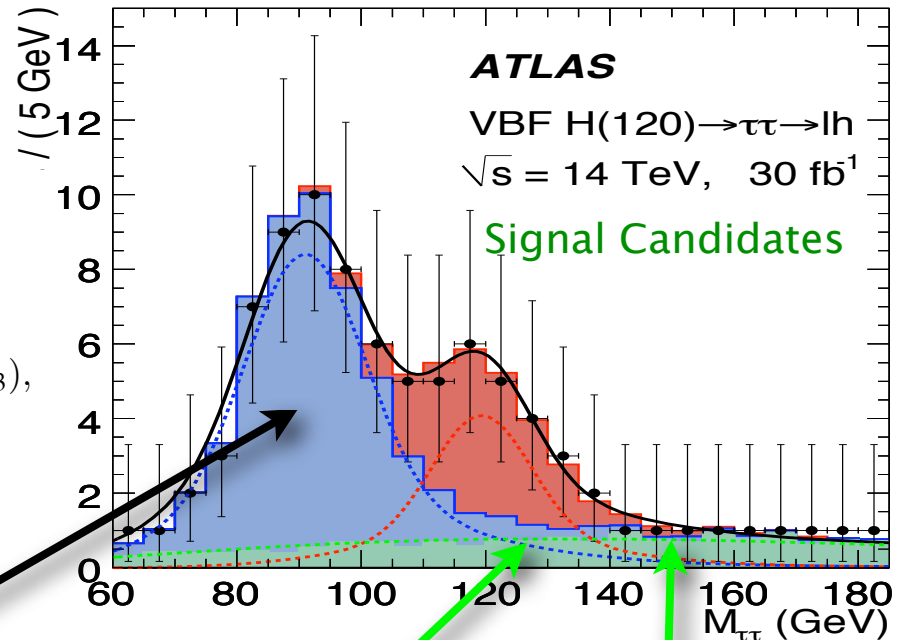
The profile approach works asymptotically and only if your parametrization is sufficiently flexible.

# Simultaneous Fitting Strategy



Simultaneous fit to signal and control samples control background shape and normalization from data

$$L(\text{data}|\mu, M_H, \nu) = L_{\text{track}}(\text{track multiplicity}|r_{\text{QCD}}) \\ \times L_Z(Z + \text{jets control}|\sigma_Z) \\ \times L_{\text{QCD}}(\text{QCD control}|a_0, a_1, a_2, a_3) \\ \times L_{s+b}(\text{signal candidates}|\mu, M_H, \sigma_H, \sigma_Z, r_{\text{QCD}}, a_0, a_1, a_2, a_3),$$



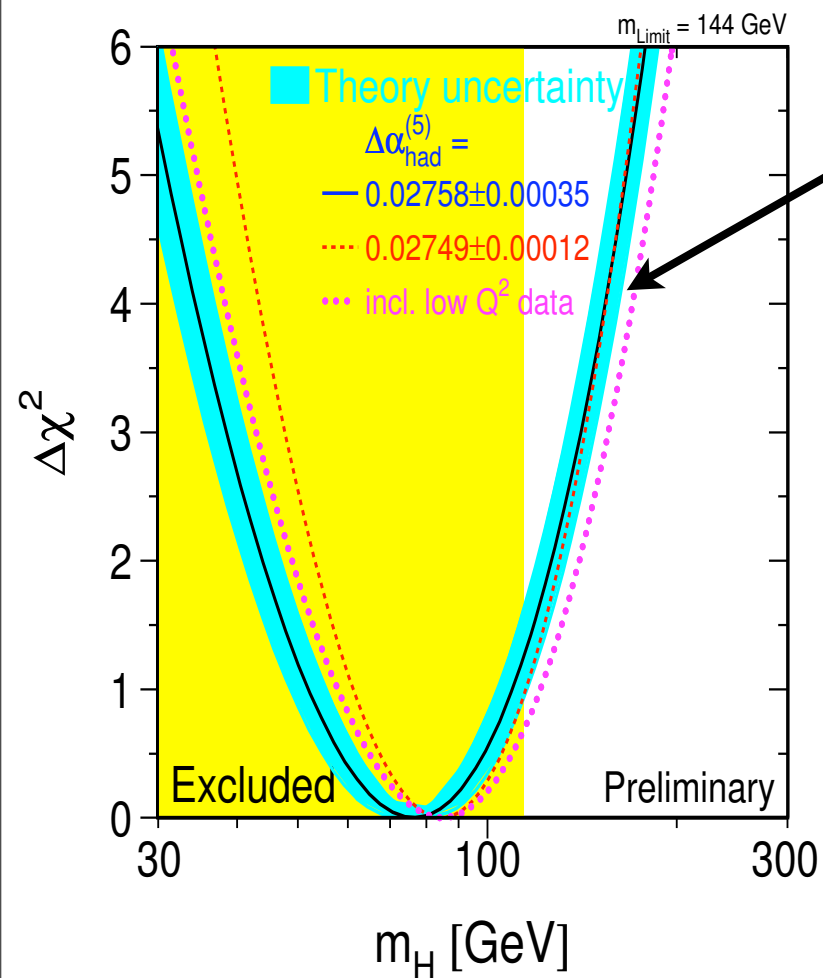
# Examples of Published Likelihoods



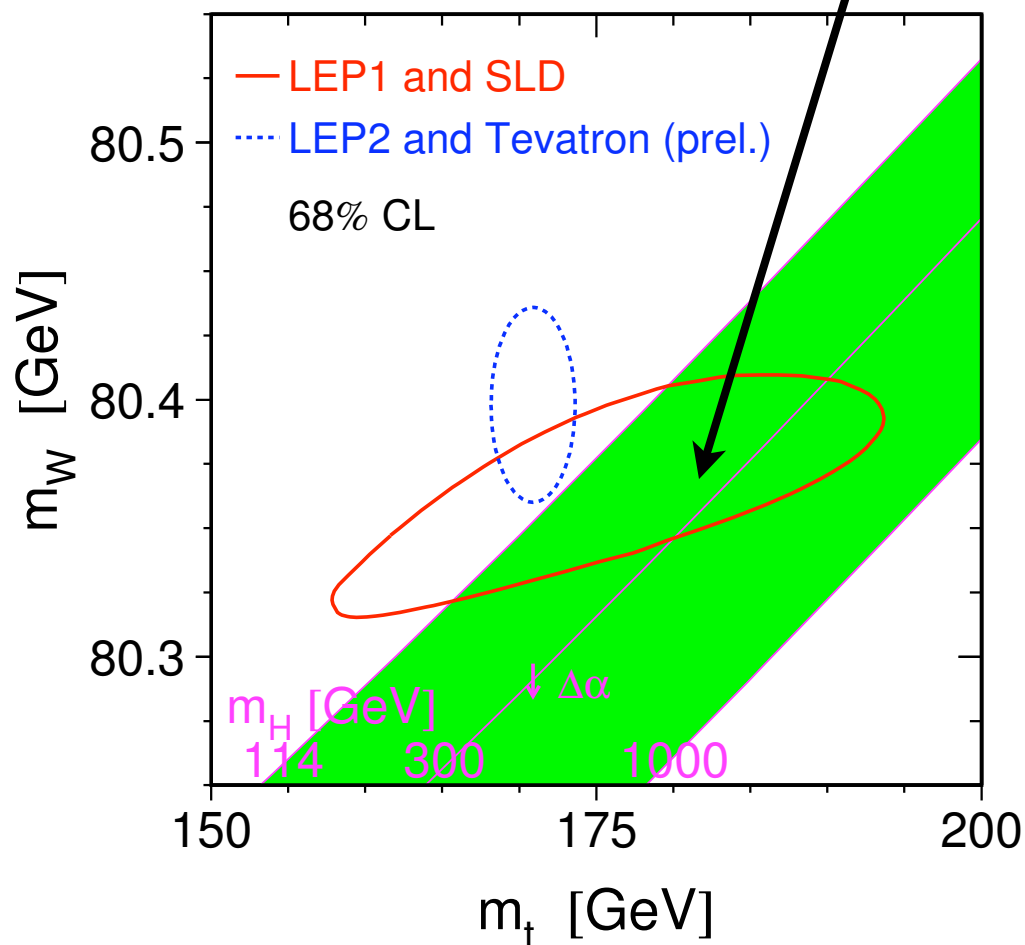
In statistical meetings for experiments, we agreed to publish likelihood functions

You can find examples of published likelihoods in 1D

In 2-D you just get the contours



Surely we can do better!

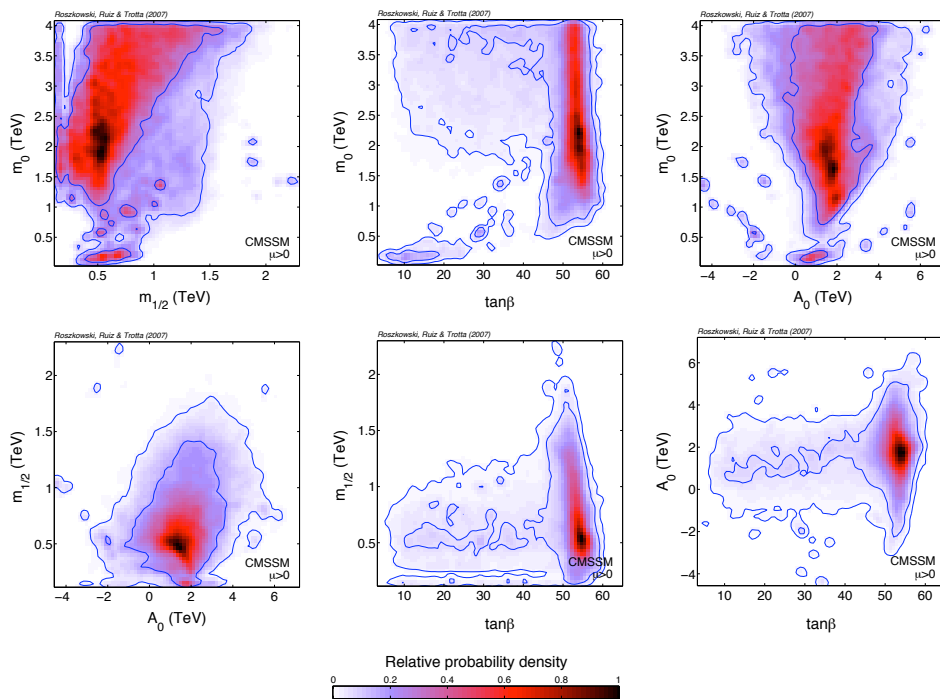
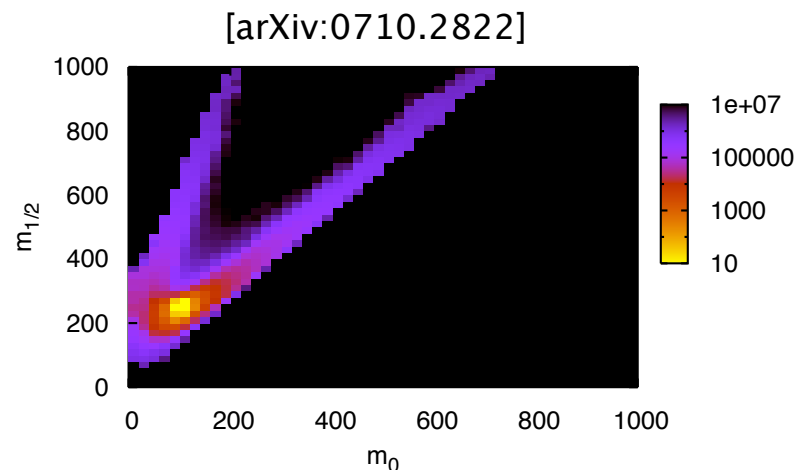


# Publishing Likelihood Maps

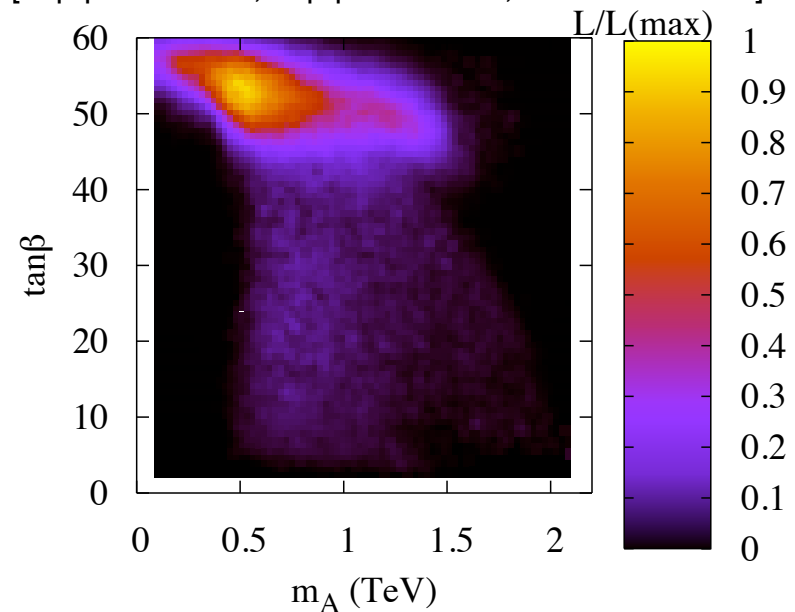


From existing measurements, several groups have done weather forecasting for LHC:

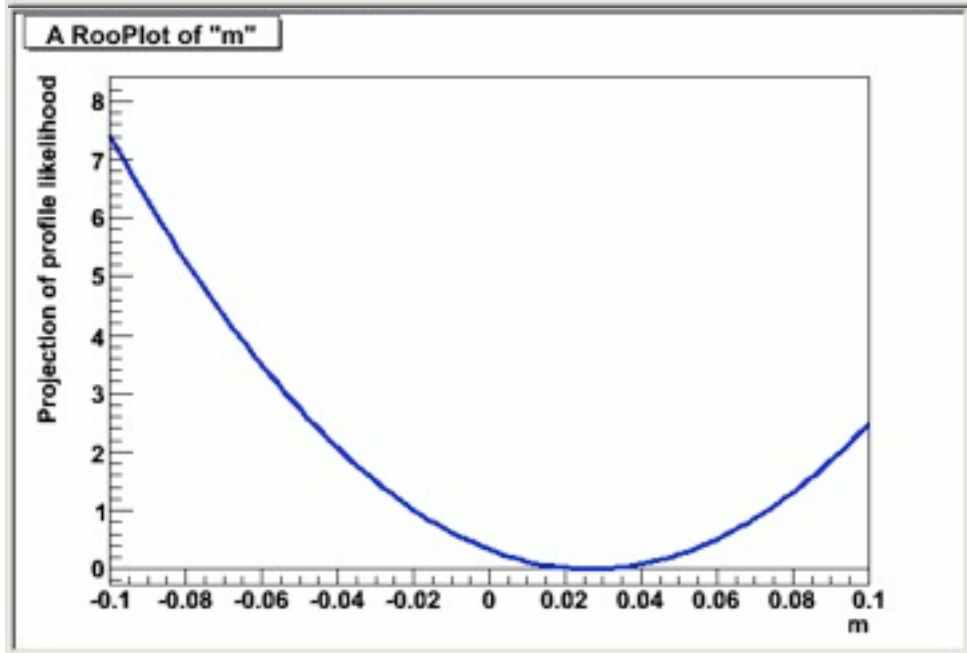
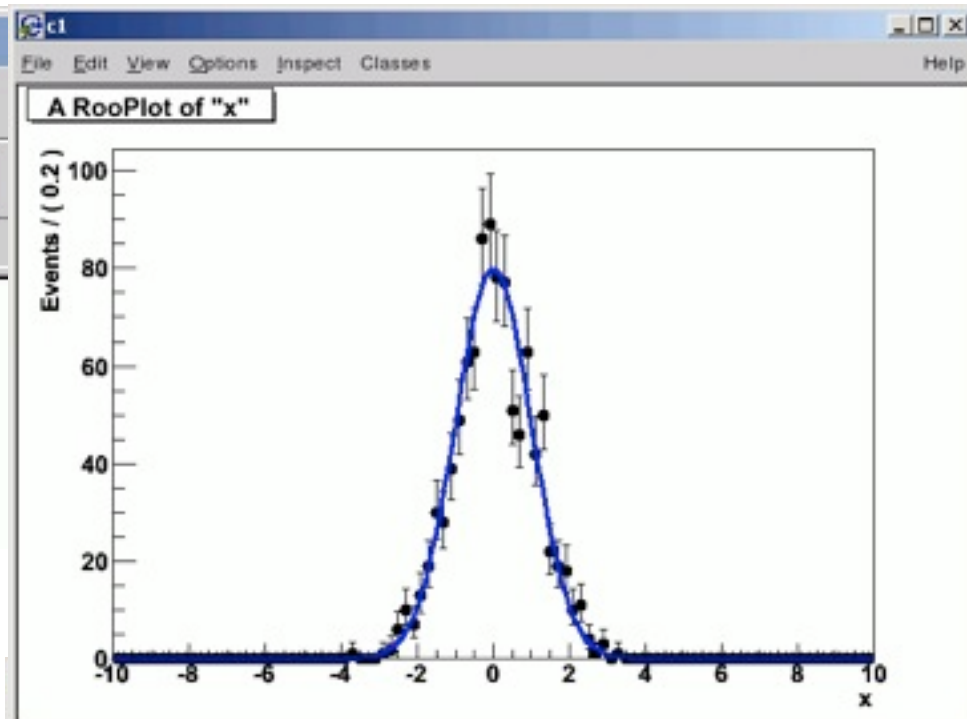
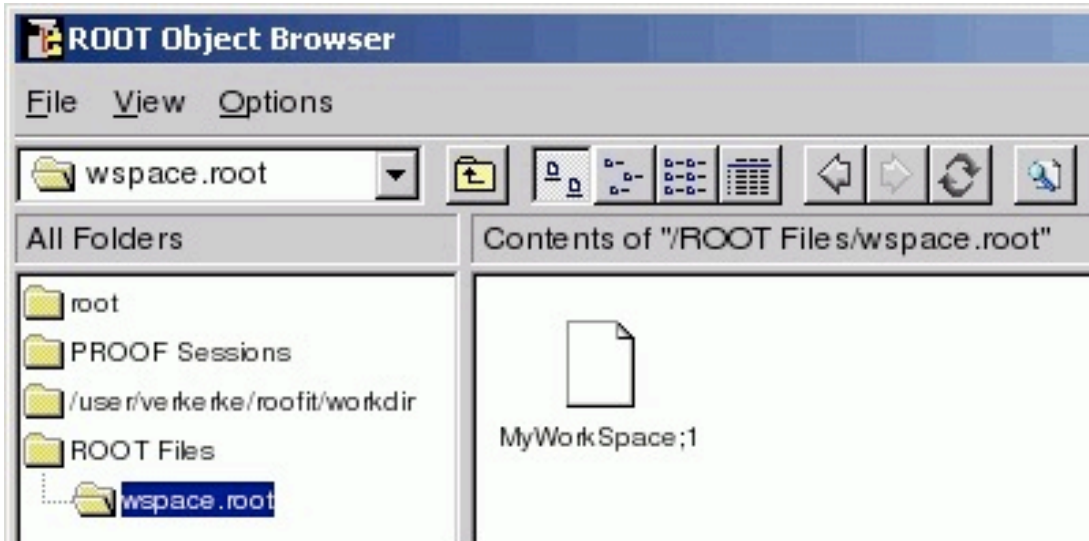
- ▶ KISMET publishing full likelihood maps  
<http://users.hepforge.org/~allanach/benchmarks/kismet.html>
- ▶ Ideally, inputs to FITTINO and SFITTER would be a true likelihood map



[hep-ph/0507283, hep-ph/0601089, arXiv:0705.0487]



# Example of Digital Publishing in RooFit/RooStats



RooFit's Workspace now provides the ability to save in a ROOT file the full likelihood model and the minimal data necessary to reproduce likelihood function.

It's generic, we decide how to parametrize the model.

Need this for combinations, we should publish them to some repository!

# Combining Results: An Example



## A combination example

- Combining 'ATLAS' and 'CMS' result from persisted workspaces

```
Read ATLAS workspace { TFile* f = new TFile("atlas.root") ;  
                      RooWorkspace *atlas = f->Get("atlas") ;
```

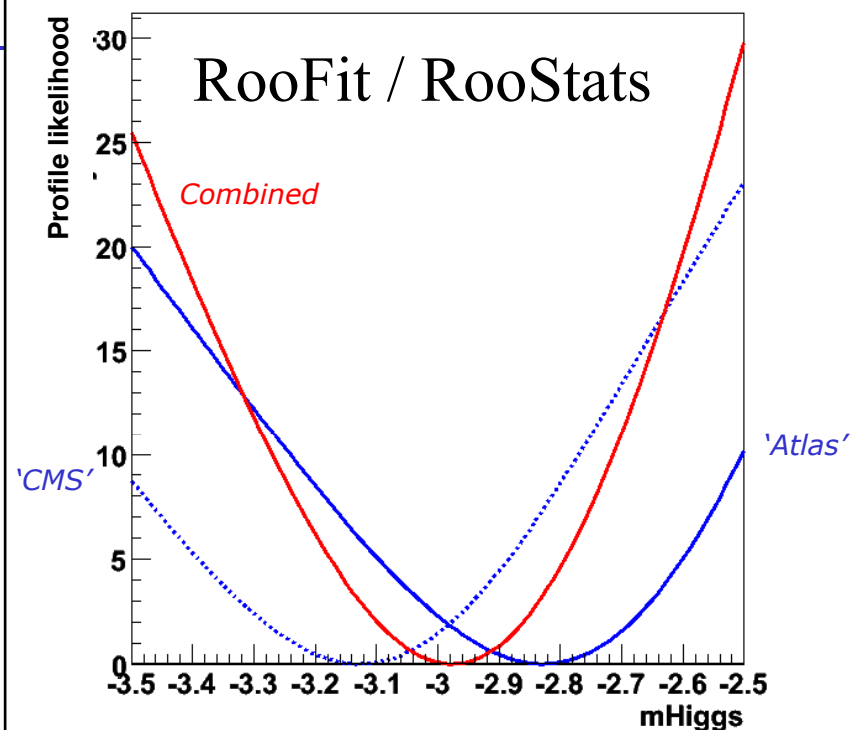
```
Read CMS workspace { TFile* f = new TFile("cms.root") ;  
                    RooWorkspace *cms = f->Get("cms") ;
```

```
Construct combined LH { RooAddition n11Combi("n11Combi", "n11 CMS&ATLAS",  
                                             RooArgSet(*cms->function("n11"), *atlas->function("n11"))) ;
```

```
Construct profile LH in mHiggs { RooProfileLL p11Combi("p11Combi", "p11", n11Combi, *atlas->var("mHiggs")) ;
```

```
Plot Atlas, CMS, combined profile LH { RooPlot* mframe = atlas->var("mHiggs")->frame(-3.5, -2.5) ;  
                                       atlas->function("n11")->plotOn(mframe) ;  
                                       cms->function("n11")->plotOn(mframe, LineStyle(kDashed)) ;  
                                       p11Combi.plotOn(mframe, LineColor(kRed)) ;  
                                       mframe->Draw() ; // result on next slide
```

Wouter Verkerke, NIKHEF



By using the workspace, it is easy to share results, ideal for combinations.

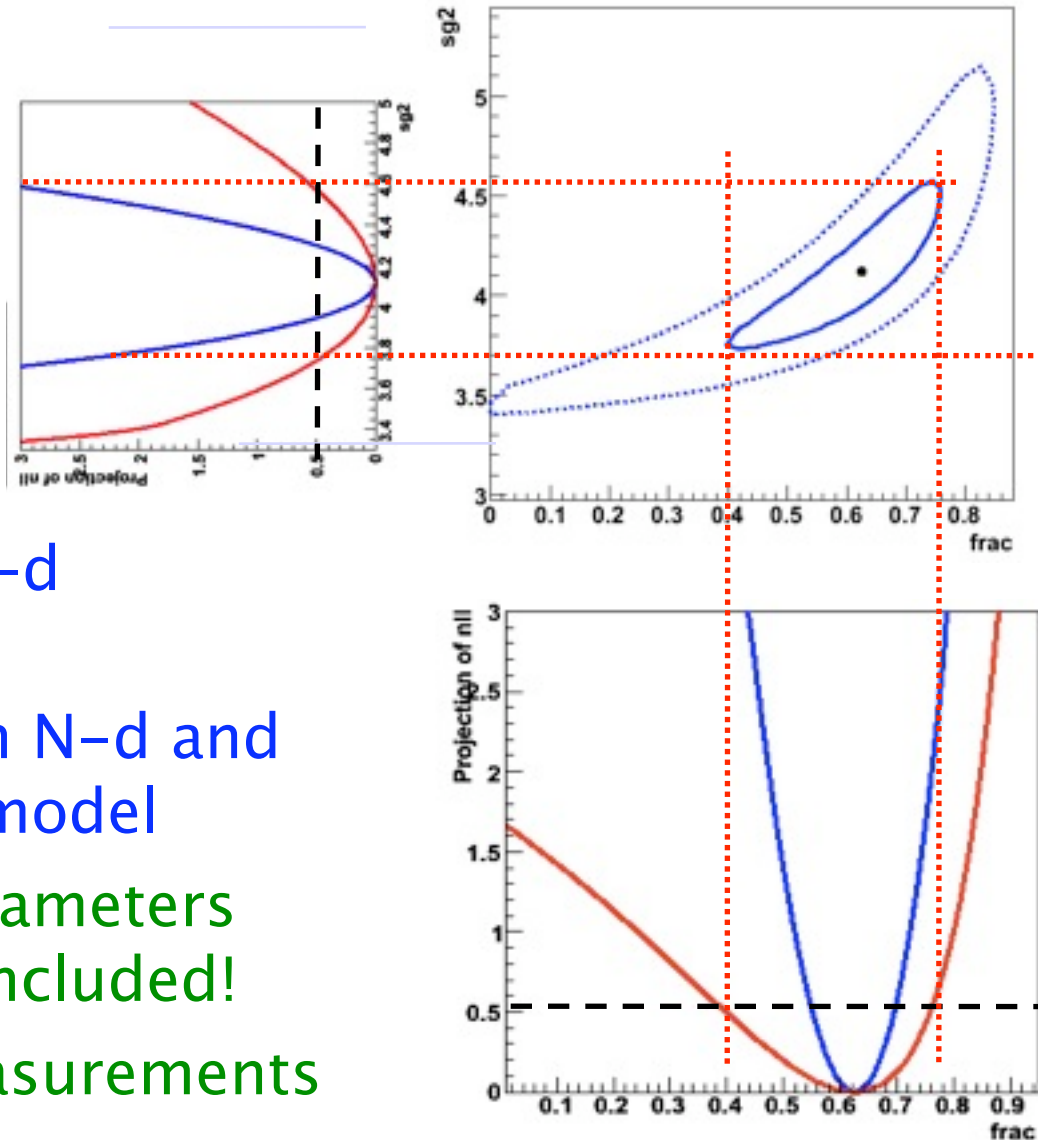
Example above shows opening an 'atlas' and 'cms' workspace, and performing a combined fit to a common parameter with profile likelihood.





## Extracting Contours from these results

The workspace can represent arbitrary models with many parameters of interest and many nuisance parameters



- One can plot 2-d contours, 1-d likelihood functions
- One can evaluate likelihood in N-d and use to evaluate a theoretical model
- If the model has nuisance parameters for systematics, they will be included!
- Easy to combine multiple measurements

Taken from Wouter Verkerke, NIKHEF